Hexapod design for COSAMIRA testing

Description

In order to do rapid testing of Cosamira IMUs and monitoring software, an hexapod needs to be designed and prototyped.

This hexapod can displace a Cosamira unit in all 6-axis (x, y, z accelerations and rotations). Therefore we can quickly assess that internal IMUs are correctly working but also that they are correctly in line with the unit-housing. The hexapod could also be used in a R&D phase for reproducing specific train speed-profile in order to trigger some monitoring/safety algorithms and test their behavior in a controlled environment.

This thesis is three folds:

The first goal is to build and resolve all the necessary invert kinematic in order to drive the platform in a cartesian/spherical coordinate system.

The second part will be to develop the necessary physical interface between the computer that runs the kinematic equations and the actuators.

The third and last goal consist in designing the mechanical parts to link the platform and actuators together.

Required knowledge:

- * basics of mechanics/ kinematic simulation
- * electronics
- * 3D modelling
- * Python or else

If you are interested in this topic, please also register this on the Televic website at: https://www.televic.com/en/careers/internships-and-students so we can confirm the topic is still available.

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Trains and trams all around the world are equipped with Televic Rail solutions, from New Zealand to Canada, from China to the United States, from India to Belgium, England and France.

Contact

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https://www.televic.com/en/careers/internships-and-students

Nature of the work

Level	Specialty	Type of work.	Location	Type of activities	Num of students
Academic Master, Bachelor, Master	Electronics / Hardware, Mechanical / Product design, Software	Research: 10% Implem.: 70% Experim.: 20%	Televic	Design, Experimenting, Programming	1

